

## **About Cubroid Blocks**







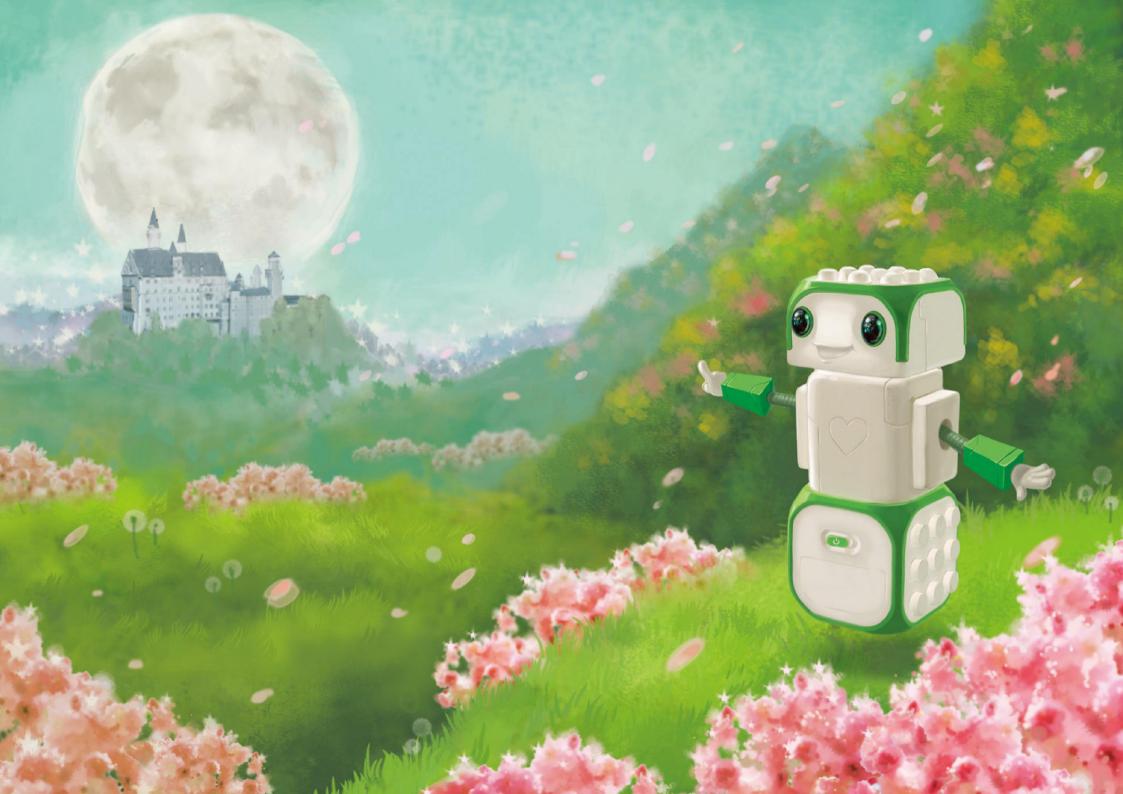
LED Block











#### Robot Education

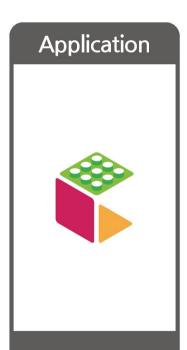
### Goal

- 1 Control the Block
- 2 Understand the Characteristics of DC Motor Block

### Play 1

Take control of the DC motor block back and forth by using the Go Cubroid app.











# Robot Education

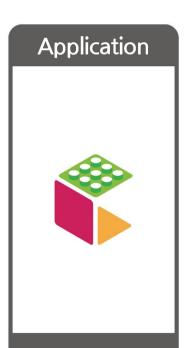
### Goal

- 1 Control the Block
- 2 Understand the Characteristics of LED Block

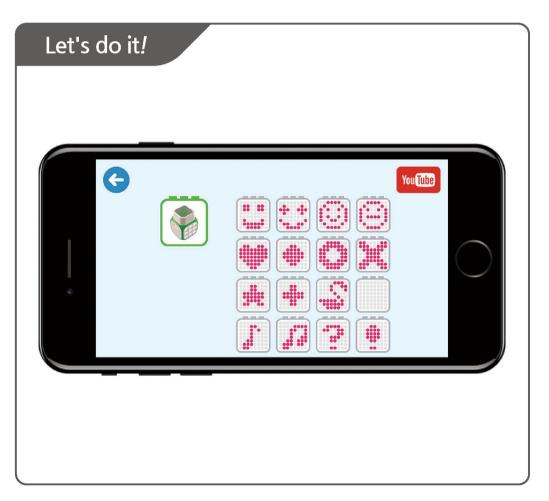
### Play 2

Use the Go Cubroid app and LED blocks to express various facial expressions.











#### Goal

- **O** Coding
- 2 Understand sequential and repeated statements

### Play 3

Code the DC motor to move forward, backward, and stop repeatedly by using the Coding Cubroid app and the DC motor block.











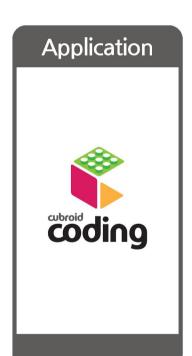
#### Goal

- **O** Coding
- 2 Understand sequential and repeated statements

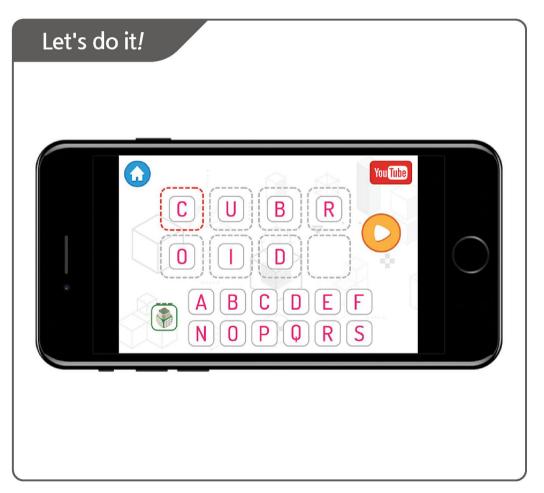
### Play 4

Use the LED blocks to express 'I LOVE YOU'.











## Robot Education

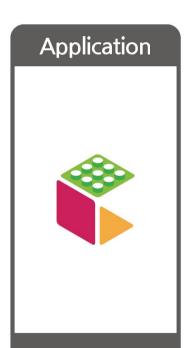
#### Goal

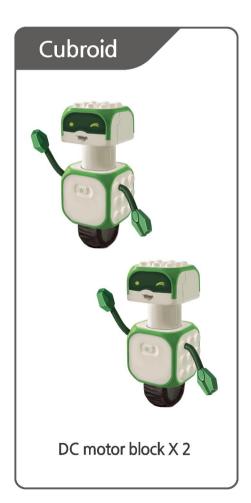
- Control two blocks
- 2 Understand the characteristics of DC motor block

### Play 5

Utilize two DC motor blocks to build your car and navigate forward, backward, left, and right.











## Robot Education

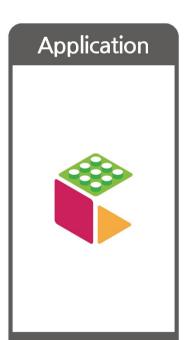
#### Goal

- Control three blocks
- 2 Understand the characteristics of LED block
- 3 Understand the characteristics of DC motor block

### Play 6

Assemble the LED block and two DC motor blocks to create and control the robot.











#### Goal

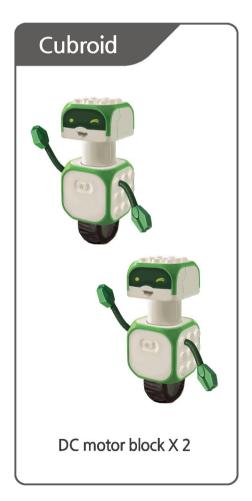
- Coding
- 2 Understand sequential and repeated statements

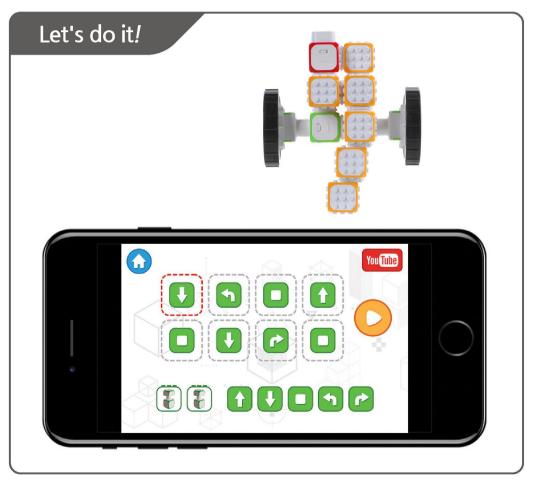
### Play 7

Create a car
by using Coding Cubroid app
and two DC motor blocks,
and code to move forward, left, right,
backward, and stop in sequence repeatedly.











#### Goal

- **O** Coding
- 2 Understand sequential and repeated statements

### Play 8

Assemble LED blocks and two DC motor blocks to create robots and code them for fun.











#### Goal

- Coding
- 2 Understand the selection statement (conditional statement)
- Understand the characteristics of Proximity sensor block DC motor block

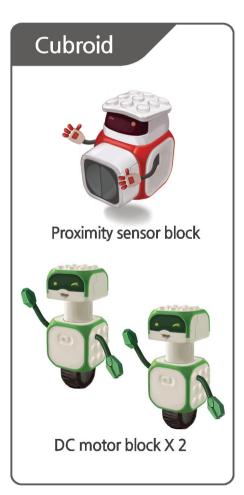
### Play 9

Assemble the proximity sensor block and the DC motor block to make a windmill and code to make the windmill turn when objects approach the front of the proximity sensor.













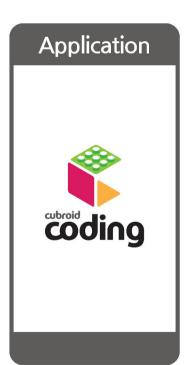
#### Goal

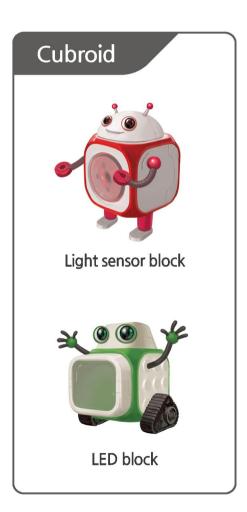
- Coding
- Understand the selection statement (conditional statement)
- Understand the characteristics of Light sensor block

### Play 10

Use the light sensor blocks and LED blocks to code the LED blocks that light up when the surroundings are dark.











#### Goal

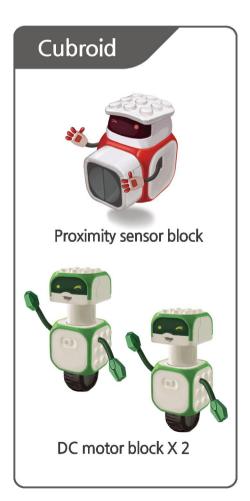
- Coding
- 2 Understand the selection statement (conditional statement)
- Understand the characteristics of Proximity sensor block

### Play 11

Assemble the proximity sensor block and the DC motor block to make a car and code an autonomous vehicle to avoid when objects approach the front of the proximity sensor.













Cubroid Play 1 - 11 classes First Edition January 31, 2017

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